

Simulating and Understanding Multi-Soliton Solutions to NLS Enze Xiao, Bingxue An, Satwik Pani, Harsha Venkatesh, Xinran Yu (Team Leader) and Katelyn Leisman (Faculty Mentor) University of Illinois at Urbana-Champaign

- Gain Familiarity with the nonlinear Schrödinger (NLS) equation
- Use paper by Biondini and Kovačič to help understand and observe behavior and form of the NLS at nonzero boundary cases
- Fix and change code from Zero Boundary Condition (ZBC) solution to new solution for nonzero Boundary Conditions (NZBC)
- Create animations for multi-soliton solutions for the NLS at NZBC
- Let q(x,t) be a function dependent on x and t. A partial derivative of q is a function which gives the change in q when slightly change one variable while keeping the others fixed. Here we will use subscripts to denote partial derivatives: q_x for the change in q with respect to x (keeping t fixed), and q_t for the change in q with respect to t. Note that we can take the partial deriviative of a function twice, which is denoted q_{xx} or q_{tt} . A Partial Differetial Equation(PDE) is then an equation which includes the partial derivatives of q.
- A linear differential equation is an equation which only has terms with either zero or one factors of either q or a derivative of q. The nonlinear Schrödinger Equation is nonlinear nonlinear equations are more common.
- The nonlinear Schrödinger equation is

$$iq_t + q_{xx} + 2(|q|^2 - q_0^2) = 0$$

the origin. We looked at the case where $q_0 \neq 0$.



• The solution to the PDE is in general, an infinite sum. If we look at the solutions with N terms, then we have an N-solition solution. Each term corresponds to one soliton. Visually, a soliton will be a bump in the graph. For example, Figure 1 has 3 solitons.

After arriving at a solution for the Nonzero Boundary Condition (NZBC) equation, a natural way to inspect and investigate the differences of boundary conditions is to compare terms and see how they are different or similar and what impact the differences might have.

Examining the single soliton case for the NZBC and ZBC we noticed a few things that were important aspects of the NLS equation.

A major difference we noticed was that important quantities included in the calculation of the ZBC solution were different in the NZBC solution.

	ZBC	
q(x,t)	$Ae^{i(V^2-A^2)t-iVx-i\psi}\operatorname{sech}(Ax-2AVt-\delta)$	q_0
Velocity	V	
Important Variables	Norming constant involves a scaling by amplitude A , shift of δ , and phase ψ	•

shape.



Figure 1: *Example solution for NLS with ZBC*

Stationary Soliton

If the eigenvalue of the solution is purely imaginary, then this solution is stationary. The equation requires that the eigenvalue z cannot be i. Figure 2 shows 3 example soliton solutions.

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There are a few directions to take in the future: • Animate the solution for a general N-soliton solution. • Use animations to investigate dispersion relations, which are relations between spacial

frequency and temporal frequency.

References

G. Biondini and G. Kovačič. Inverse scattering transform for the focusing nonlinear schrödinger equation with nonzero boundary conditions. Journal of Mathematical Physics, 55, 02 2014. doi: 10.1063/1.4868483.

